



ET-M8196F

Ethernet Remote Unit with High-speed, DSP-based, 6-axis Motion Control Module

Figure 5

- Remote control via Modbus TCP
- DSP-based motion control module
- Pulse output rate: 4 MHz (Max.)
- Maximum encoder input frequency: 12 MHz
- Independent 6-axis motion control
- 2 to 6 axes linear / 2 to 3 axes circular / 3 axes helical interpolation functions
- Continuous interpolation
- 4-step home mode with auto-searching
- Synchronized start motion
- Programmable T/S-curve acceleration and deceleration
- Software limit protection
- Software FIFO for arbitrary curve motion
- High-speed position latch
- High-speed compare trigger and auto-increment compare mode
- Expandable remote I/O:
 - 128 DI and 128 DO via a two-wire FRnet interface







■ Introduction

The **ET-M8196F** is a compact remote motion control device which uses Modbus TCP as its communication protocol. The ET-M8196F acts as a server in a Modbus TCP network and supports all standard Modbus function codes defined by the Modbus TCP protocol. Nowadays many PCs have got limited PCI slots; therefore the ET-M8196F can be used to replace PCI motion control cards. The ET-M8196F has got two Ethernet ports which allow daisy chaining.

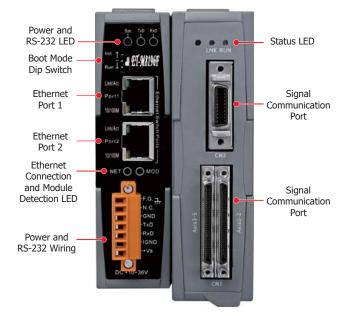
The motion controller of the ET-M8196F consists of an Ethernet communication module and a 6-axis motion control card. A digital signal processor (DSP) is the brain of the motion controller which calculates the commanded move trajectory and manages supervisory control by monitoring the limits and emergency stops to ensure safe operation. I/O control output (e.g. latch, compare, encoder counter etc.) is realized in a Field Programmable Gate Array (FPGA).

The motion controller is suitable for general-purpose motion control applications. In additions to its wide speed range, this intelligent motion controller also has a variety of built-in motion control functions, such as 2 to 6 axes linear interpolation, 2 to 3 axes circular interpolation, 3 axes helical interpolation, T/S-curve acceleration/deceleration, and automatic home search, etc.

In addition the ET-M8196F acts as an FRnet master and can control up to 128 digital outputs and 128 digital inputs. FRnet is a two-wire serial bus and has a scan interval of 0.72 ms and it is specifically designed for easy and cost effective wiring. ICPDAS provides a large range of FRnet I/O terminal boards and modules.

An application programming interface (API) for communicating with the ET-M8196F motion controller is being provided. This enables the user's program on the host computer to easily interact with the motion controller. A software utility for Ethernet configuration and basic motion settings and execution is part of the software package.

Hardware



ET-M8196F Interface Functions

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Specifications

| Software OS Support Windows 7/8/10 32/64 bit Visual C++ lib/DLL, C#, VB.Net DLL, Delphi, Visual Basic 6.0, BCB 5.0, 6.0 Utility EzGo Utility Hardware Connector 68-pin VHDCI and 20-pin SCSI-II General No. of Axes 6 Motion Control Type Servo Update Rate Position Control Mode Command Type Auto-Home Search Input Signal Filter Axis I/O Servo Interface Output Latch Input Mechanical Switch Input Position Compare Output Servo Interface Input Incremental and absolute mode SVON, ALM_RST, ERC High-Speed 5 V TTL or 24 V open collector Servo Interface Input INP, ALM, RDY Encoder Input | | | | | |
|--|-------------------------|----------------------------|--|--|--|
| OS Support Windows 7/8/10 32/64 bit Visual C++ lib/DLL, C#, VB.Net DLL, Delphi, Visual Basic 6.0, BCB 5.0, 6.0 Utility EzGo Utility Hardware Connector 68-pin VHDCI and 20-pin SCSI-II General No. of Axes 6 Motion Control Type DSP Based Speed Profile T/S-curve Servo Update Rate 2 KHz Position Control Mode Command Type Pulse Command Auto-Home Search Input Signal Filter Axis I/O Servo Interface Output High-Speed 5 V or 24 V NPN Mechanical Switch Input Position Compare Output Incremental and absolute mode SVON, ALM_RST, ERC High-Speed 5 V TTL or 24 V open collector Servo Interface Input INP, ALM, RDY | Model | ET-M8196F | | | |
| Development Development Development Development Visual C++ lib/DLL, C#, VB.Net DLL, Delphi, Visual Basic 6.0, BCB 5.0, 6.0 Utility EzGo Utility Hardware Connector 68-pin VHDCI and 20-pin SCSI-II General No. of Axes 6 Motion Control Type DSP Based Speed Profile T/S-curve Servo Update Rate 2 KHz Position Control Mode Command Type Pulse Command Auto-Home Search Input Signal Filter Yes Axis I/O Servo Interface Output Latch Input High-Speed 5 V or 24 V NPN Home, Limit+/-, Near Home, Emergency Position Compare Output Or 24 V open collector Servo Interface Input INP, ALM, RDY | Software | | | | |
| Development VB.Net DLL, Delphi, Visual Basic 6.0, BCB 5.0, 6.0 Utility EzGo Utility Hardware Connector 68-pin VHDCI and 20-pin SCSI-II General No. of Axes 6 Motion Control Type DSP Based Speed Profile T/S-curve Servo Update Rate 2 KHz Position Control Mode Command Type Pulse Command Auto-Home Search Input Signal Filter Yes Axis I/O Servo Interface Output High-Speed 5 V or 24 V NPN Mechanical Switch Input Position Compare Output Servo Interface Input Nex Home, Emergency High-Speed 5 V TTL or 24 V open collector Servo Interface Input INP, ALM, RDY | OS Support | | | | |
| Hardware Connector General No. of Axes Motion Control Type Speed Profile Servo Update Rate Position Control Mode Command Type Auto-Home Search Input Signal Filter Axis I/O Servo Interface Output Position Compare Output Servo Interface Input Position Compare Output Servo Interface Input Mechanical Switch Input Mechanical Servo Interface Input Mechanical Input M | Development | VB.Net DLL, Delphi, | | | |
| Connector General No. of Axes Motion Control Type Servo Update Rate Position Control Mode Command Type Auto-Home Search Input Signal Filter Axis I/O Servo Interface Output Position Compare Output Position Compare Output Servo Interface Input Mechanical Switch Input Mechanical Servo Interface Input Mechanical Input | Utility | EzGo Utility | | | |
| General No. of Axes Motion Control Type Servo Update Rate Position Control Mode Command Type Auto-Home Search Input Signal Filter Axis I/O Servo Interface Output Mechanical Switch Input Position Compare Output Servo Interface Input Motion Control Mode T/S-curve 2 KHz Incremental and absolute mode Pulse Command Yes Input Signal Filter Yes Axis I/O Servo Interface Output High-Speed 5 V or 24 V NPN Home, Limit+/-, Near Home, Emergency High-Speed 5 V TTL or 24 V open collector Servo Interface Input INP, ALM, RDY | Hardware | | | | |
| No. of Axes Motion Control Type Speed Profile Speed Profile T/S-curve Servo Update Rate Position Control Mode Command Type Auto-Home Search Input Signal Filter Axis I/O Servo Interface Output Latch Input Mechanical Switch Input Position Compare Output Servo Interface Input Nechanical Servo Interface Input INP, ALM, RDY | Connector | | | | |
| Motion Control Type Speed Profile Speed Profile Servo Update Rate Position Control Mode Command Type Auto-Home Search Incremental and absolute mode Pulse Command Auto-Home Search Input Signal Filter Yes Axis I/O Servo Interface Output Latch Input Mechanical Switch Input Position Compare Output Servo Interface Input Near Home, Emergency High-Speed 5 V TTL or 24 V open collector Servo Interface Input INP, ALM, RDY | General | | | | |
| Speed Profile Servo Update Rate Position Control Mode Command Type Auto-Home Search Input Signal Filter Axis I/O Servo Interface Output Latch Input Mechanical Switch Input Position Compare Output Servo Interface Input Figh-Speed 5 V TTL or 24 V open collector Servo Interface Input T/S-curve 1 Incremental and absolute mode Pulse Command Yes Yes SYON, ALM_RST, ERC High-Speed 5 V or 24 V NPN Home, Limit+/-, Near Home, Emergency High-Speed 5 V TTL or 24 V open collector Servo Interface Input INP, ALM, RDY | No. of Axes | 6 | | | |
| Servo Update Rate Position Control Mode Command Type Auto-Home Search Input Signal Filter Axis I/O Servo Interface Output Latch Input Mechanical Switch Input Position Compare Output Servo Interface Input Servo Interface Input Servo Interface Input Position Compare Output Servo Interface Input Position Compare Output Incremental | Motion Control Type | DSP Based | | | |
| Position Control Mode Incremental and absolute mode Command Type Pulse Command Auto-Home Search Input Signal Filter Axis I/O Servo Interface Output Latch Input Mechanical Switch Input Position Compare Output Servo Interface Input Incremental Incremental and absolute mode Pulse Command Yes SYON, ALM_RST, ERC High-Speed 5 V or 24 V NPN Home, Limit+/-, Near Home, Emergency High-Speed 5 V TTL or 24 V open collector Servo Interface Input INP, ALM, RDY | Speed Profile | T/S-curve | | | |
| Position Control Mode and absolute mode Command Type Pulse Command Auto-Home Search Yes Input Signal Filter Yes Axis I/O Servo Interface Output SVON, ALM_RST, ERC Latch Input High-Speed 5 V or 24 V NPN Mechanical Switch Input Position Compare Output Servo Interface Input INP, ALM, RDY | Servo Update Rate | 2 KHz | | | |
| Auto-Home Search Input Signal Filter Axis I/O Servo Interface Output Latch Input Mechanical Switch Input Position Compare Output Servo Interface Input Servo Interface Output High-Speed 5 V or 24 V NPN Home, Limit+/-, Near Home, Emergency High-Speed 5 V TTL or 24 V open collector INP, ALM, RDY | Position Control Mode | | | | |
| Input Signal Filter Axis I/O Servo Interface Output Latch Input Mechanical Switch Input Position Compare Output Svon, ALM_RST, ERC High-Speed 5 V or 24 V NPN Home, Limit+/-, Near Home, Emergency High-Speed 5 V TTL or 24 V open collector Servo Interface Input INP, ALM, RDY | Command Type | Pulse Command | | | |
| Axis I/O Servo Interface Output SVON, ALM_RST, ERC Latch Input High-Speed 5 V or 24 V NPN Mechanical Switch Input Home, Limit+/-, Near Home, Emergency Position Compare Output High-Speed 5 V TTL or 24 V open collector Servo Interface Input INP, ALM, RDY | Auto-Home Search | Yes | | | |
| Servo Interface Output SVON, ALM_RST, ERC Latch Input High-Speed 5 V or 24 V NPN Mechanical Switch Input Position Compare Output Servo Interface Input SVON, ALM_RST, ERC High-Speed 5 V or 24 V NPN Home, Limit+/-, Near Home, Emergency High-Speed 5 V TTL or 24 V open collector INP, ALM, RDY | Input Signal Filter | Yes | | | |
| Latch Input High-Speed 5 V or 24 V NPN Mechanical Switch Input Position Compare Output Servo Interface Input High-Speed 5 V or 24 V NPN Home, Limit+/-, Near Home, Emergency High-Speed 5 V TTL or 24 V open collector | | | | | |
| Mechanical Switch Input Home, Limit+/-, Near Home, Emergency High-Speed 5 V TTL or 24 V open collector Servo Interface Input INP, ALM, RDY | Servo Interface Output | SVON, ALM_RST, ERC | | | |
| Position Compare Output Near Home, Emergency High-Speed 5 V TTL or 24 V open collector Servo Interface Input INP, ALM, RDY | Latch Input | High-Speed 5 V or 24 V NPN | | | |
| Servo Interface Input INP, ALM, RDY | Mechanical Switch Input | , , , | | | |
| | Position Compare Output | | | | |
| Encoder Input | Servo Interface Input | INP, ALM, RDY | | | |
| | Encoder Input | | | | |
| Mode A/B Phase, Up/Down | Mode | A/B Phase, Up/Down | | | |

| Model | ET-M8196F | | | |
|-----------------------|------------------------------------|--|--|--|
| Ring Counter Mode | 32-bit | | | |
| Counting Rate | 12 MHz | | | |
| Counter Width | 32-bit | | | |
| Pulse Output | | | | |
| Mode | CW/CCW, PULSE/DIR, A/B Phase | | | |
| Counter Width | 32-bit | | | |
| Rate | 4 MPPS (Max.) | | | |
| Interpolation | | | | |
| Cicular | Any 2 to 3 axes (up to 3 groups) | | | |
| Continuous | Yes | | | |
| Helical | 3 axes | | | |
| Linear | Any 2 to 6 axes (up to 3 groups) | | | |
| Digital Input | | | | |
| Channels | Local: 12 DI Expandable: 128 DI | | | |
| Isolation | 2500 Vrms (with DN-8368) | | | |
| Digital Output | | | | |
| Channels | Local: 3 DO Expandable: 128 DO | | | |
| Isolation | 2500 Vrms (with DN-8368) | | | |
| Ethernet | | | | |
| Protocol | Modbus TCP | | | |
| Power | | | | |
| Input Range | +24V | | | |
| Mechanical | | | | |
| Dimensions (mm) | 65 x 121 x 125 (W x L x H) | | | |
| Environment | | | | |
| Operating Temperature | 0 ~ +60 °C | | | |
| Storage Temperature | -20 ∼ +80 °C | | | |
| Humidity | 10 ~ 90% RH, Non-condensing | | | |

■ Ordering Information

| ET-M | 8196F | Ethernet Remote Unit with High-speed, DSP-based, 6-axis Motion Control Module | |
|------|-------|---|--|
|------|-------|---|--|

Accessories

| DN-8368UB | Photo-isolated Universal Snap-on wiring terminal board |
|------------------------|--|
| DN-8368GB | Photo-isolated General-purpose wiring terminal board |
| DN-8368MB | Photo-isolated Snap-on wiring terminal board for Mitsubishi MELSERVO-J2 servo amplifier |
| DN-20M | General purpose digital input and remote digital I\O (FRnet) extension board |
| CA-MINI68-15 | 68-pin VHDCI to SCSI-II Connector Cable, Length 1.5 M |
| CA-SCSI20-M1/M3/M5 | 20-pin SCSI-II Male connector cable (for Mitsubishi J2 series motor), Length 1 M / 3 M / 5 M. |
| CA-26-MJ3-15/30/50(B) | 26-pin HD D-Sub Male Cable for Mitsubishi Servo Amplifier, 1.5/3/5 M. (for MELSERVO-J3/J4Series) |
| CA-26-PA4-15/30/50(B) | 26-pin HD D-Sub Male Cable for Panasonic Servo Amplifier, 1.5/3/5 M. (for MINAS A4/A5 Series) |
| CA-26-YSV-15/30/50(B) | 26-pin HD D-Sub Male Cable for Yaskawa Servo Amplifier, 1.5/3/5 M. (for Sigma II/III/V Series) |
| CA-26-DAA2-15/30/50(B) | 26-pin HD D-Sub Male Cable for Delta A2 Servo Amplifier, 1.5/3/5 M. (for ASDA-A2 Series) |
| CA-26-DAB2-15/30/50(B) | 26-pin HD D-Sub Male Cable for Delta B2 Servo Amplifier, 1.5/3/5 M. (for ASDA-B2 Series) |
| CA-26-FFW-15/30/50 | 26-pin HD D-Sub Male Cable for Fuji Servo Amplifier, 1.5/3/5 M. (for FALDIC-W and ALPHA5 Smart Series) |
| CA-26-TTA-15/30/50 | 26-pin HD D-Sub Male Cable for Teco Servo Amplifier, 1.5/3/5 M. (for TSTA-A/A+ Series) |

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